

Application of Serpent for Fuel Assembly Bowing

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and SPERT III Static Calculations

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 - Monte-Carlo Calculations for 2D Mini-cores with additional Inter-Assembly Gap
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Introduction

The Bowing Phenomenon

- Fuel assembly bowing has been observed in PWR since the mid-90s
- Deformations in C-, S-, and W-shape have been observed
- Bowing caused by
 - Irradiation creep
 - Mechanical forces (hold down springs, interaction with neighboring fuel assemblies)
 - Thermal-hydraulic forces
- Mitigation achieved by use of stiffer structure materials and appropriate reshuffling

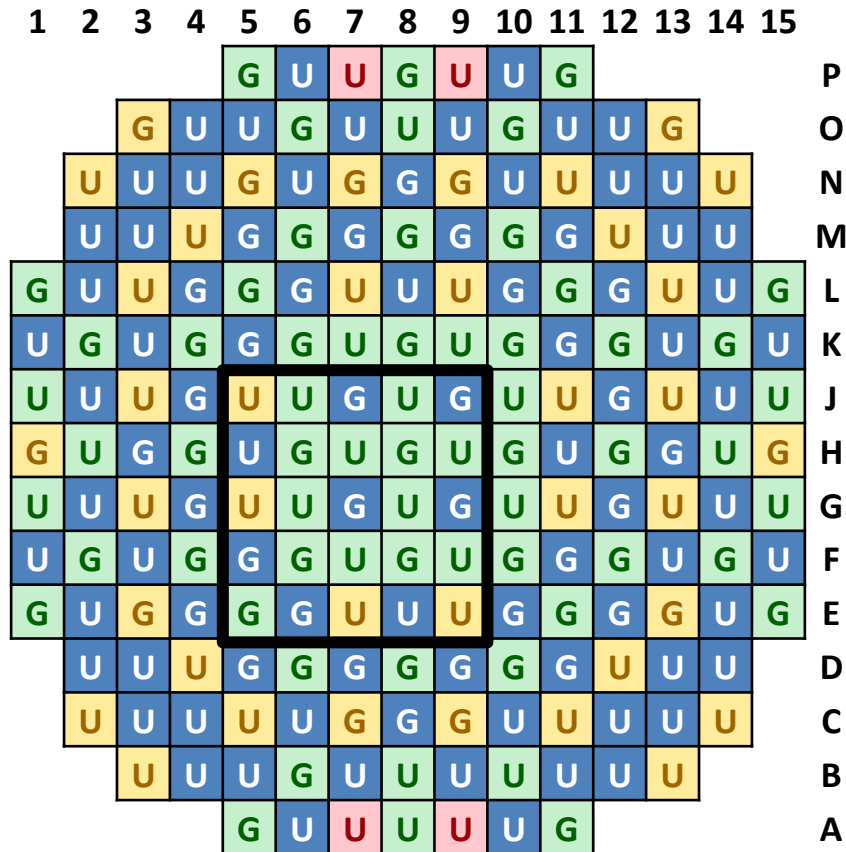
Fuel assembly bowing changes inter-assembly gap and local fuel/moderator ratio
→ impact on power of fuel pins of the first and second row

The power changes in the edge pin rows cannot be detected by the in-core detectors, therefore

- Calculations by operators necessary to confirm safety margins under bowing conditions
- Start of a research project at GRS in 2016

Mini core selection from a Pre-KONVOI cycle

Core Layout

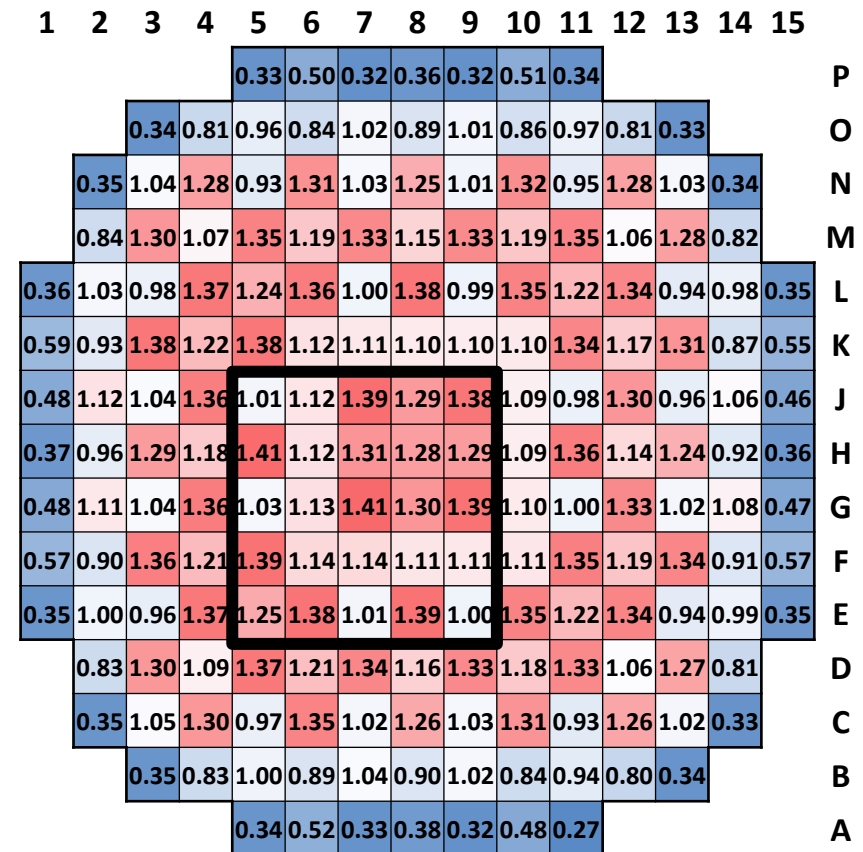


■ fresh
■ once burnt

■ twice burnt
■ thrice burnt

U: UOX fuel assembly
G: UO₂-Gd₂O₃ fuel assembly

Assembly Powers @BOC



FA power
(GRS core simulator KMACS)

Scenarios under examination

Burnup in the mini-core [MWd/kgHM]:

Fresh fuel – 0.0 MWd/kgHM

0 EFPD (BOC)

7 EFPD

5	6	7	8	9	
U	U	G	U	G	J
U	G	U	G	U	H
U	U	G	U	G	G
G	G	U	G	U	F
G	G	U	U	U	E

5	6	7	8	9	
26.3	16.3	0.0	12.4	0.0	J
0.0	17.4	12.3	15.1	12.4	H
25.7	16.3	0.0	12.4	0.0	G
0.0	17.3	15.3	17.5	16.2	F
16.6	0.0	26.4	0.0	26.3	E

5	6	7	8	9	
26.6	16.6	0.4	12.8	0.4	J
0.4	17.8	12.7	15.5	12.8	H
26.0	16.6	0.4	12.8	0.4	G
0.4	17.6	15.6	17.8	16.6	F
17.0	0.4	26.7	0.4	26.6	E

Scenario:	Fresh	BOC (no Xe)	7 EFPD (Xe equilibrium)
Boron concentration [ppm]	500.0	1576.5	1250.0
Moderator density [kg/m ³]	730.62	724.833	724.833
Moderator temperature [K]	571.15	572.71	572.71
Fuel temperature [K]	950.0	779.89	779.89

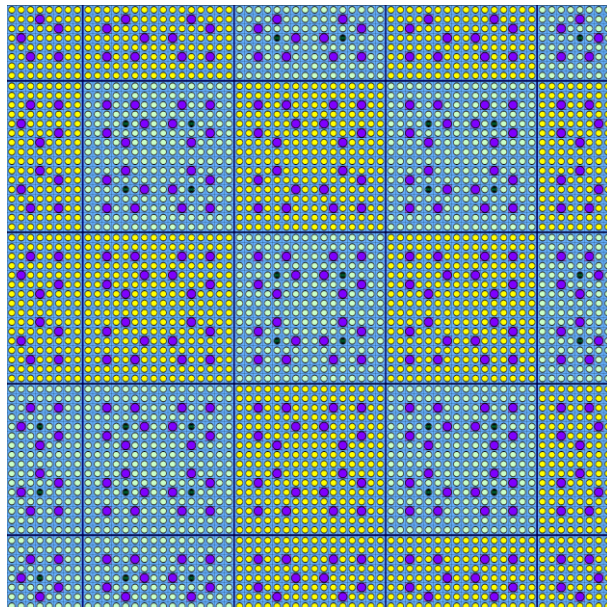
Scenarios under examination (2)

- Nominal case:
- Additional inter-assembly gap:
 - 5 mm
 - 10 mm
 - 15 mm
- Calculations with Serpent Monte Carlo

5	6	7	8	9	
U	U	G	U	G	J
U	G	U	G	U	H
U	U	G	U	G	G
G	G	U	G	U	F
G	G	U	U	U	E

Additional inter –
assembly gap in
x direction

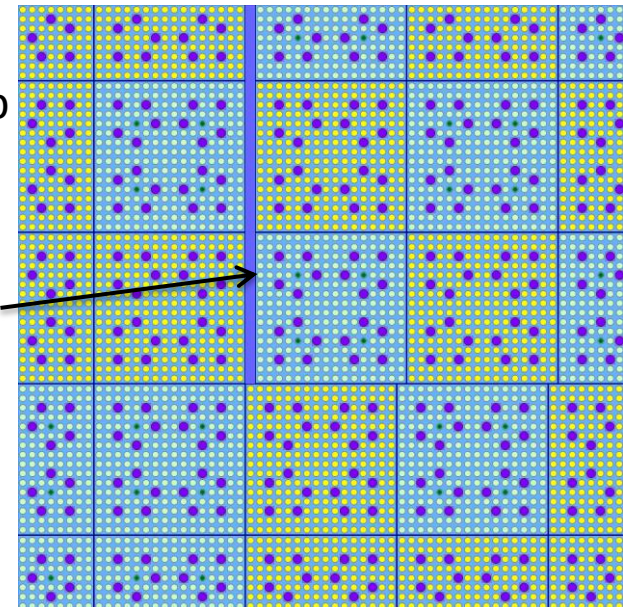
Nominal case



Nominal
inter-assembly gap



Maximum gap in x direction



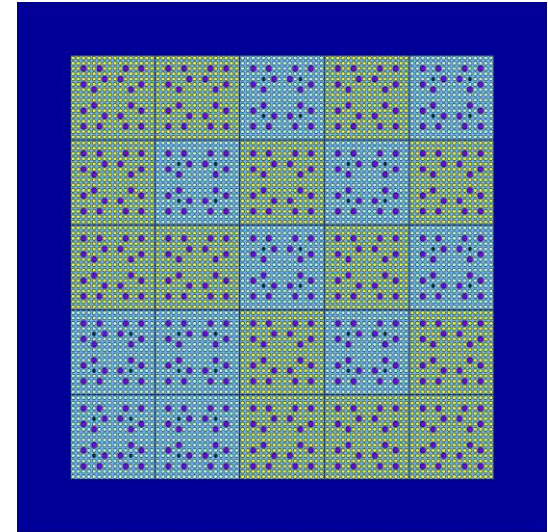
Additional
gap



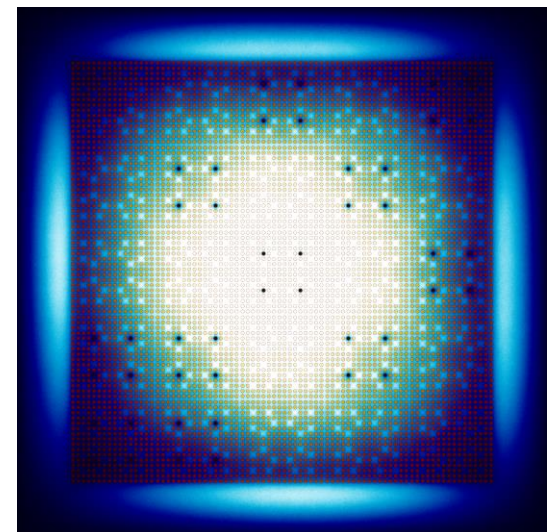
Mini-core Model – Boundary Conditions (1/3)

- Vacuum BDC:
 - Fuel mass conservation while fuel assemblies are shifted into the radial reflector
 - Problem: Significant depression of the neutron flux at the core periphery
 - ⇒ unrealistic power distribution
 - ⇒ unrealistic impact of the fuel assembly bowing in the centre of the core

MC-Model with fresh fuel:

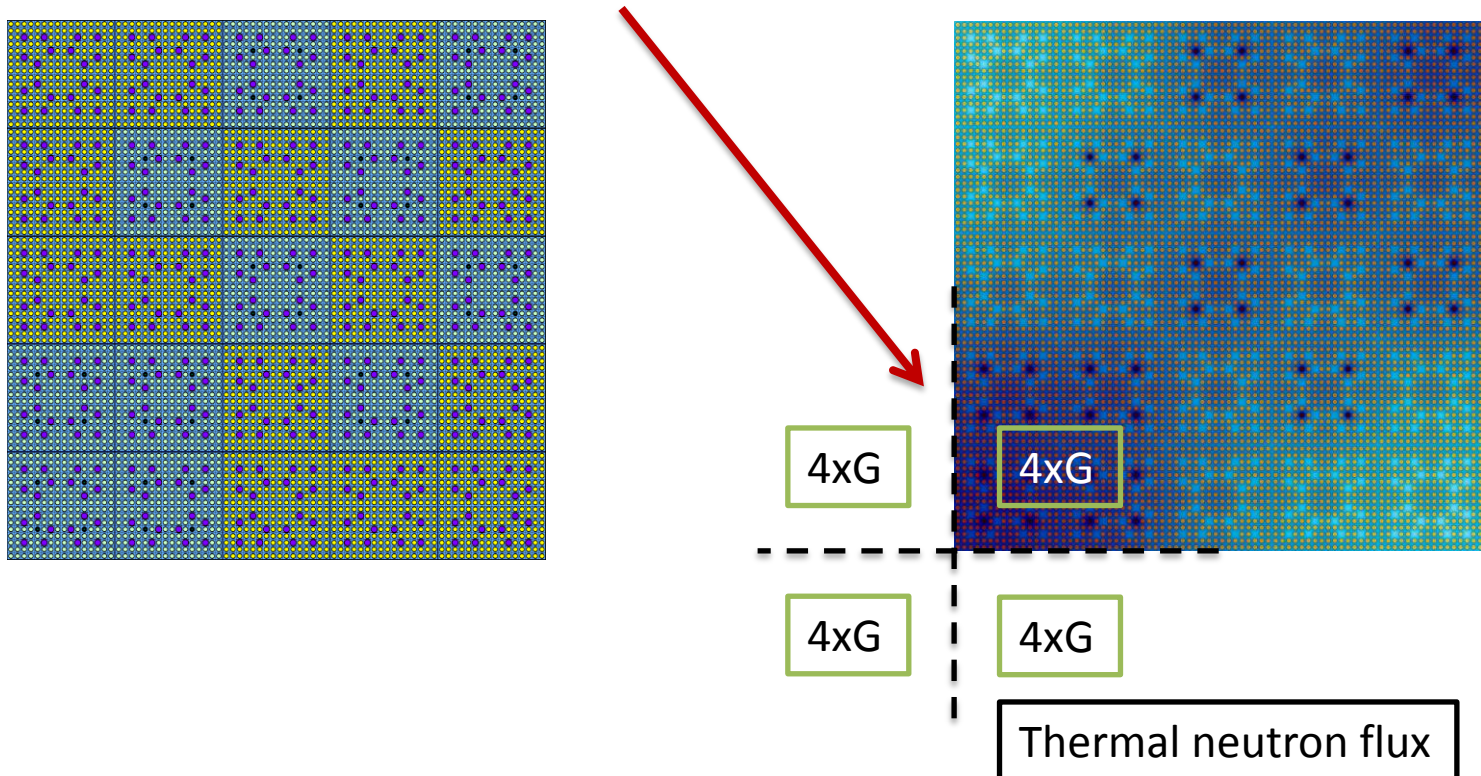


Thermal neutron flux



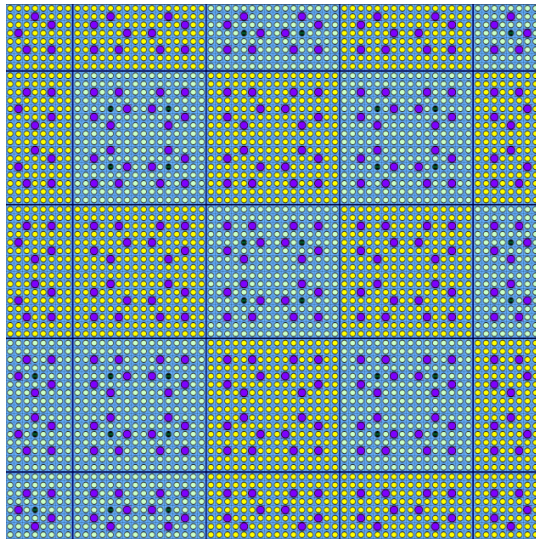
Mini-core Model – Boundary Conditions (2/3)

- Reflective BDC:
 - Uniform neutron flux distribution
 - Important for comparing power distributions:
Fuel is shifted outside the model
 - Problem: Significant depression of the neutron flux at the corner with Gd fuel assemblies

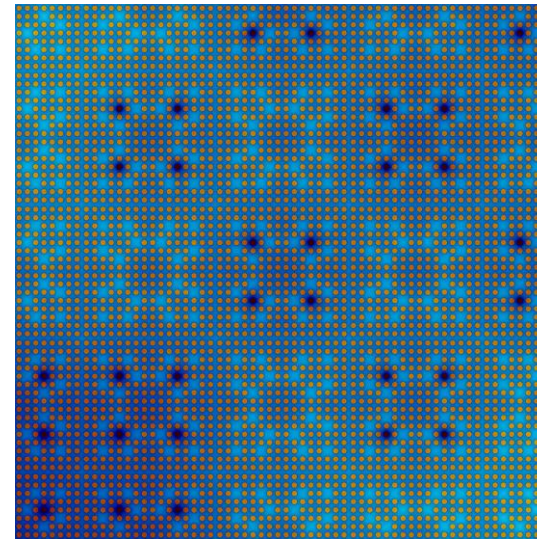


Mini-core Model – Boundary Conditions (3/3)

- Mini-core model truncated:
 - Only half of the outer assemblies is modelled
 - Reflective BDC
 - More uniform neutron flux distribution compared to the fully modelled 5x5 lattice
 - Important for comparing power distributions: Fuel is shifted outside the model



Half fuel assembly



Thermal neutron flux

Mini-core Model - Calculation Details

Monte Carlo calculation details:

- 1 000 000 Neutronhistories per cycle
- 1 000 active cycles, 60 inactive cycles
- 12.32 h run time with 10 MPI Jobs
- Stat. error ~0.2 % on pin power

Power normalisation:

- To ensure comparability, the total power of the bowed models is normalised by the total power of the nominal model

Pin power increase: ratio gap power / nominal power

Scenario BOC

Additional gap: 5 mm

	Left side		Right side	
	2nd pin Row	1st pin row	1st pin row	2nd pin row
Average increase	1.03	1.08	1.09	1.04
Maximum		1.11	1.12	

Additional gap: 10 mm

	Left side		Right side	
	2nd pin Row	1st pin row	1st pin row	2nd pin row
Average increase	1.06	1.15	1.17	1.08
Maximum		1.20	1.22	

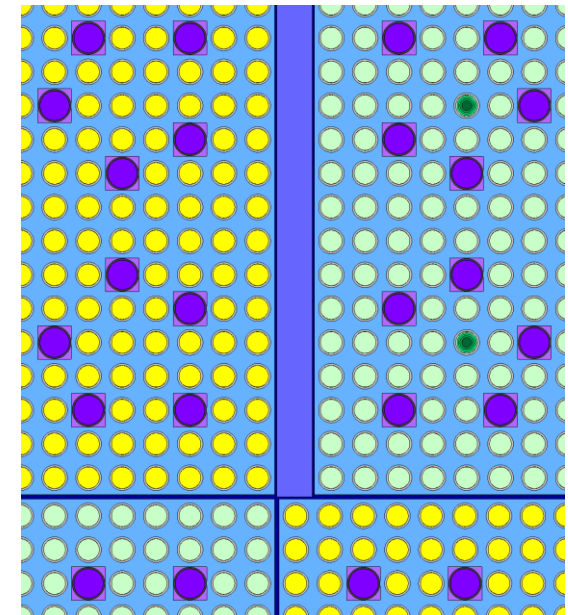
Additional gap: 15 mm

	Left side		Right side	
	2nd pin Row	1st pin row	1st pin row	2nd pin row
Average increase	1.07	1.19	1.21	1.09
Maximum		1.25	1.29	

Monte Carlo: relative statistical uncertainty of the increase approx. 0.3%.

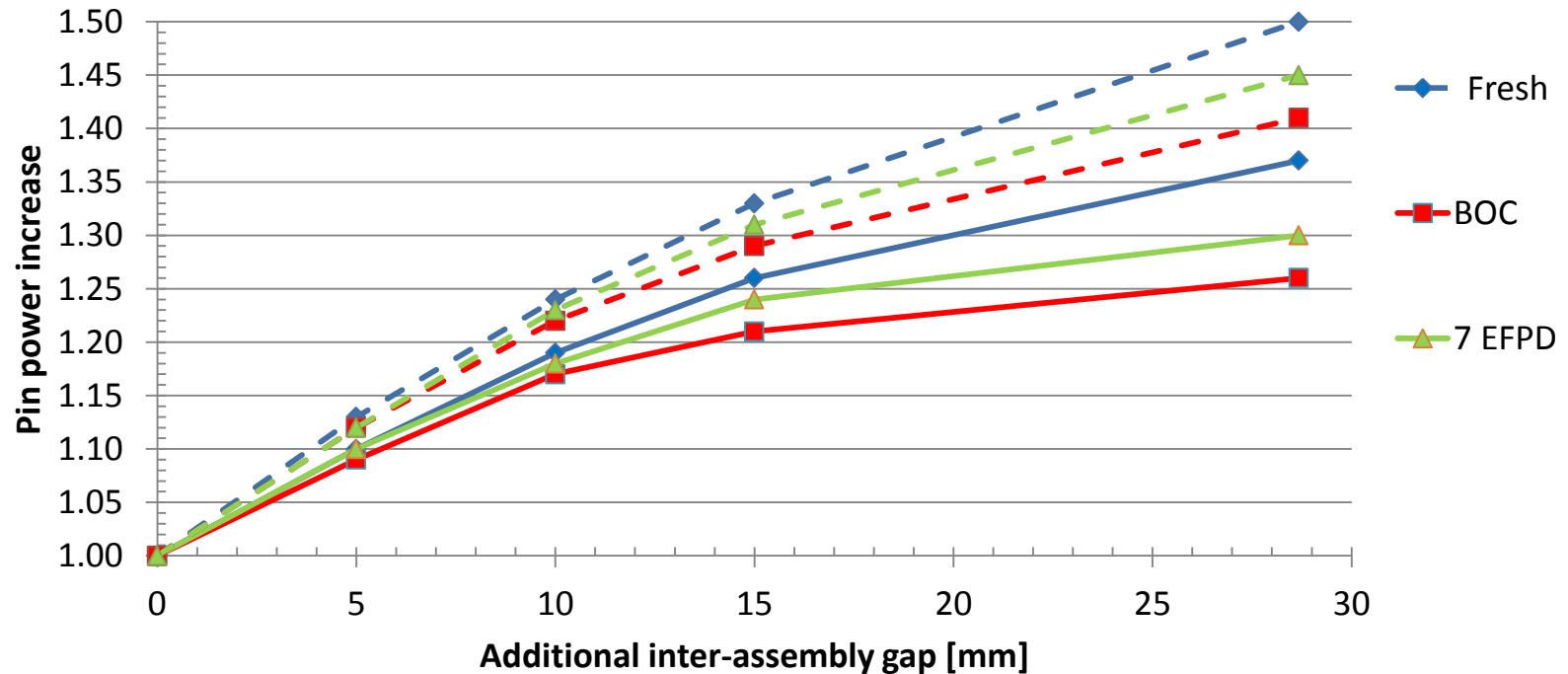
Left Side Right Side

2nd pin row 1st pin row



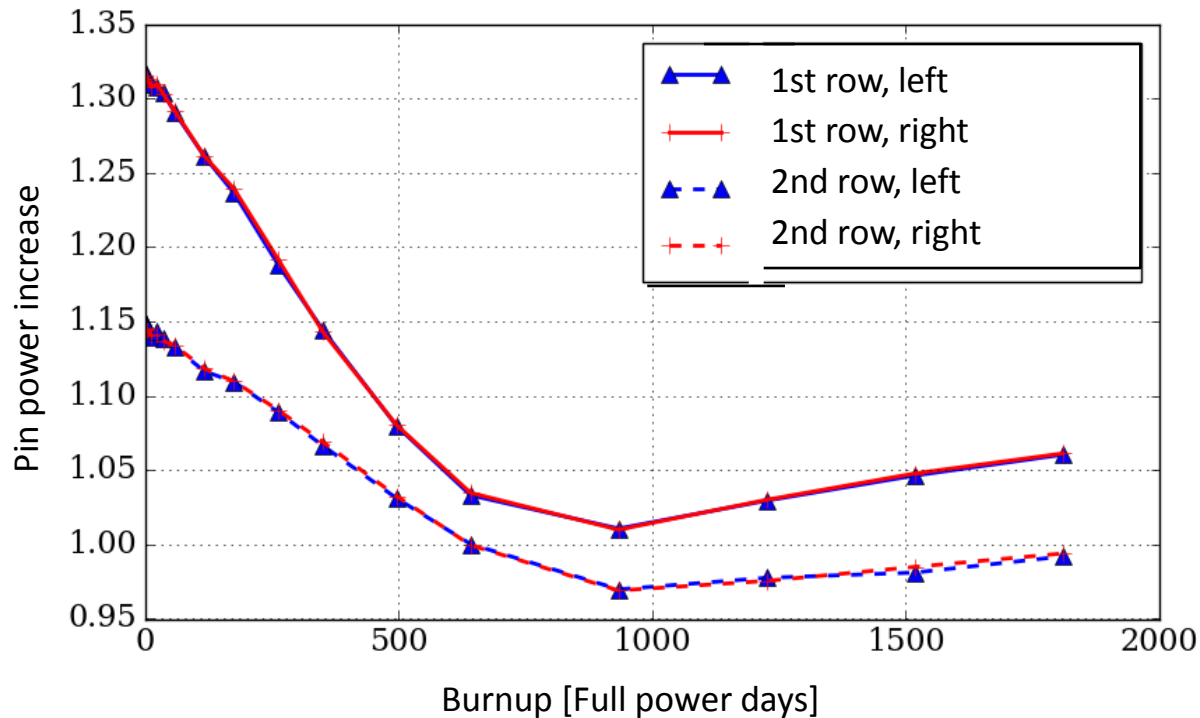
Pin power increase as a function of additional water gap

Maximum and average pin power increase
pins in the 1st row, right side

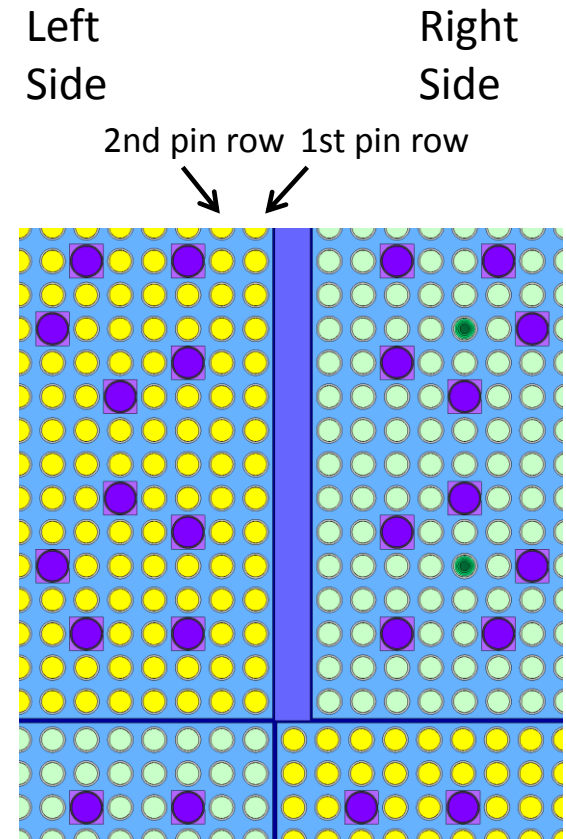


-- maximum pin power increase
— average pin power increase

Pin power increase as a function of burnup Fresh fuel @ 15mm additional gap



Average values in 1st and 2nd row, respectively

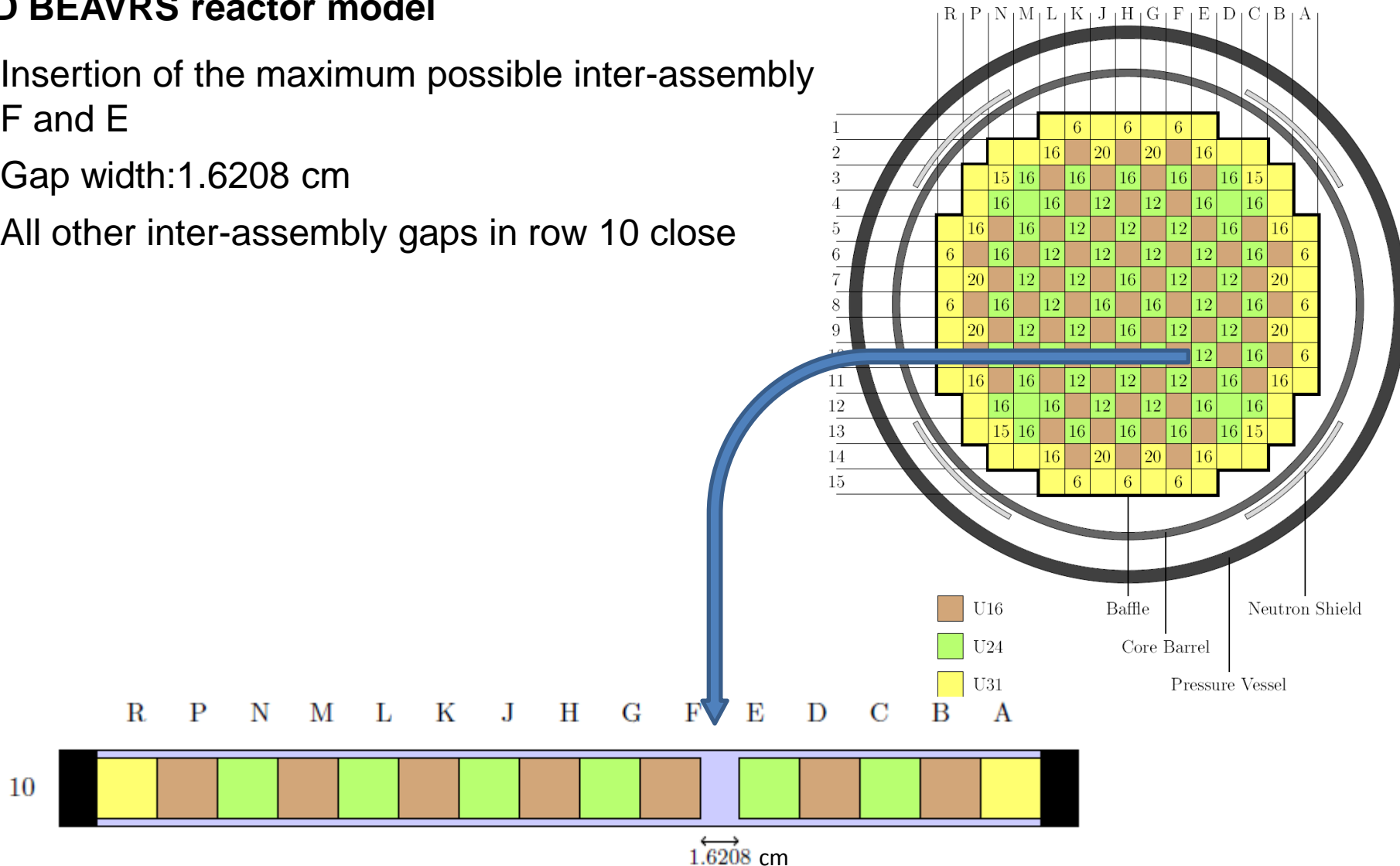


Model Extensions for the GRS Core Simulator KMACS

- 3d core simulations with TH feedback: Use of a core simulator is required
- KMACS is a classical 2-step core simulator
 1. XS generation for single fuel assemblies in infinite lattice
Interfaces to codes SCALE-NEWT, HELIOS and Serpent (provisional)
 2. Full-core calculation by a 2-group diffusion code including core thermal hydraulics (GRS Codes QUABOX/CUBBOX-ATHLET)
- Modifications required to consider fuel assembly bowing
 1. Parametrization of XS according to inter-assembly gap
 2. Modification of the nodal power calculation for the nodal diffusion code (grid is no longer quadratic)

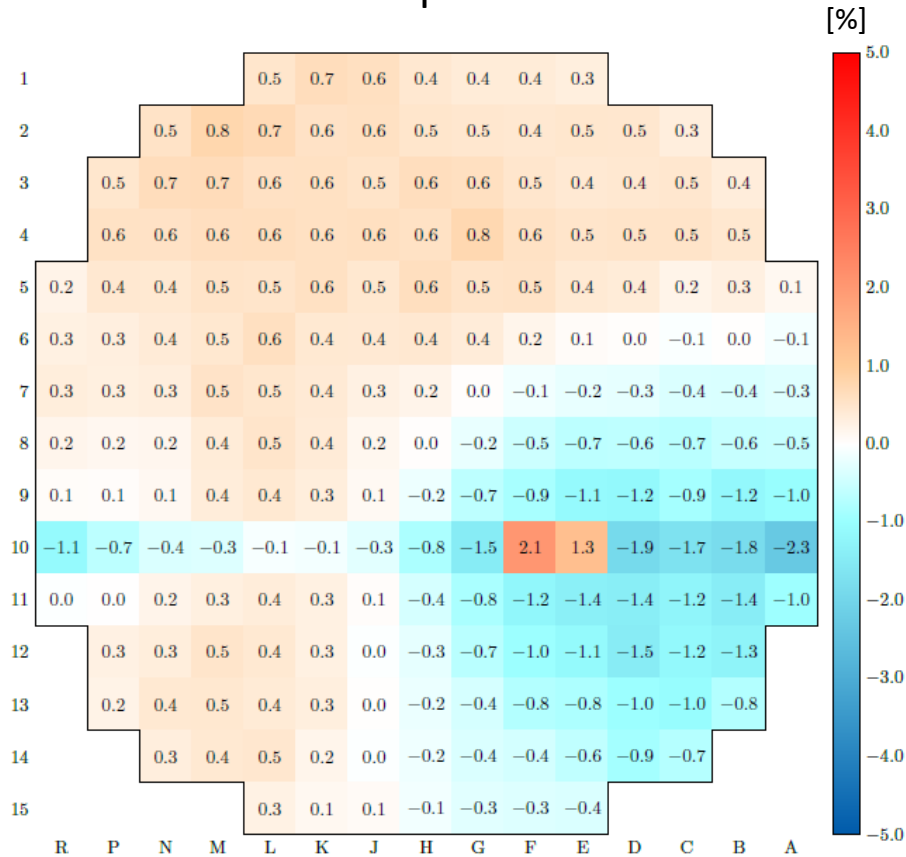
Testing gap-parametrized XS in KMACS: Single additional gap in 2D BEAVRS reactor model

- Insertion of the maximum possible inter-assembly gap F and E
- Gap width: 1.6208 cm
- All other inter-assembly gaps in row 10 close

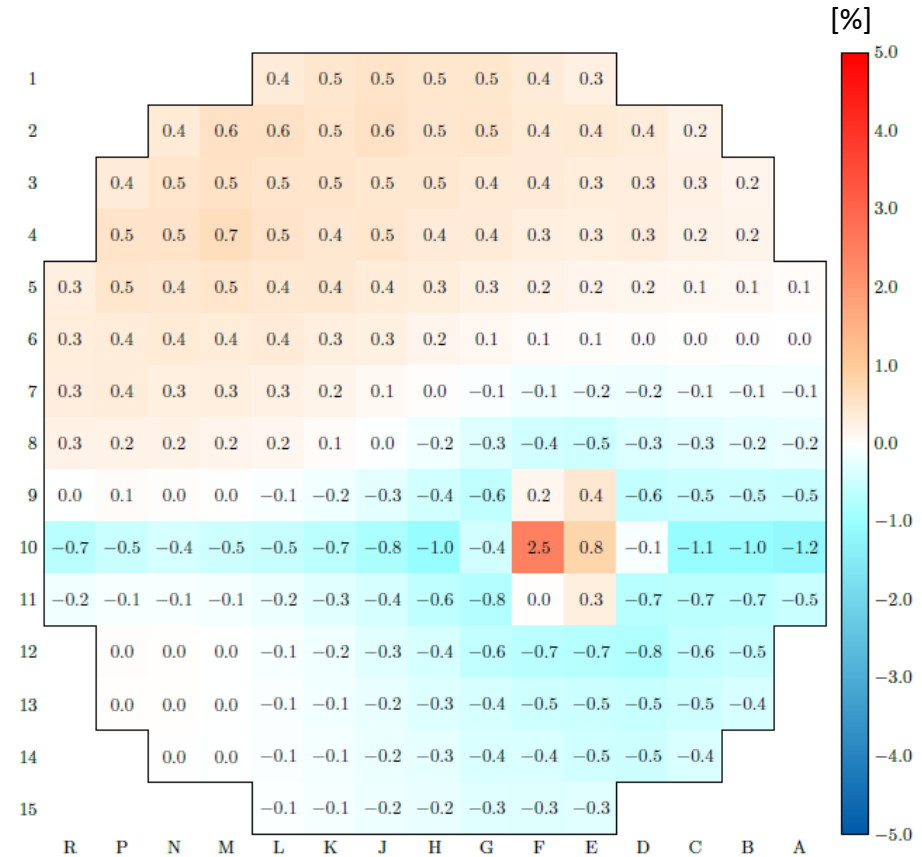


Testing gap-parametrized XS in KMACS: 2D assembly powers changes Serpent vs. KMACS

Serpent



KMACS



Assembly power changes in % of the average assembly power

Conclusions and Outlook

- Fuel assembly bow causes a change in inter-assembly gaps
- This results in
 - change of the local fuel-to-moderator ratio and
 - changes in pin powers
- Serpent Monte-Carlo Calculations yield a pin power increase of up to 34% for an additional 15mm flat gap between Pre-KONVOI $\text{UO}_2/\text{UO}_2\text{-Gd}_2\text{O}_3$ assemblies
- In approximately 400 full power days this increase burns out to 10%

- Gap-parametrized XS have been tested in GRS core simulator KMACS:
 - XS-behavior with varying inter-assembly gap similar for different UO_2 and $\text{UO}_2\text{-Gd}_2\text{O}_3$ assemblies
 - Qualitative agreement between Serpent and KMACS for assembly power changes in a 2D BEAVRS model with additional inter-assembly gap

- Next steps:
 - Extensions to 3D and more complex inter-assembly gap patterns
 - Consideration of MOX assemblies

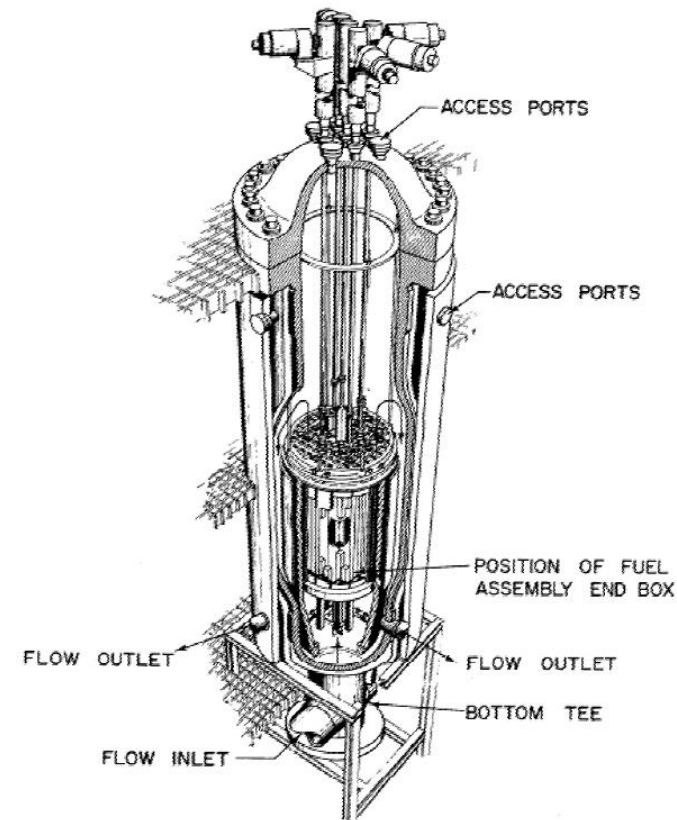
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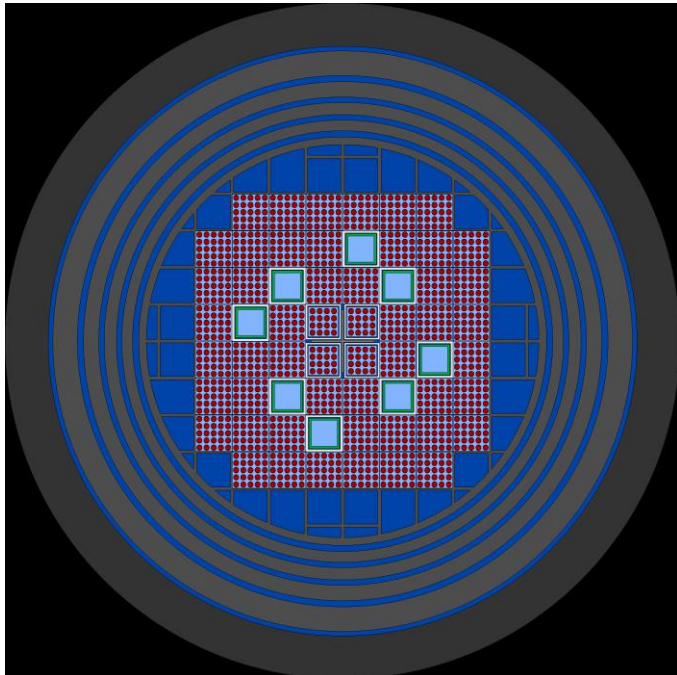
SPERT III Experiments

- Performed in the 1960's
- Analysis of reactor dynamic behaviour at rod ejection events
- PWR-like design
- Fuel: UO_2 with 4.8% enr. in U-235
- 60 fuel assemblies
 - 48 FAs with 5 x 5 fuel pins
 - 8 movable FAs: lower half 4 x 4 fuel pins, upper half absorber (stainless steel + 1.35% B-10)
 - 4 FAs with 4 x 4 fuel pins, controlled by transient rod
- Transients driven by ejection of a centrally located transient rod
- Experiments differ by inserted reactivity, reactor period and peak power
- Conditions: Cold Startup, Hot Startup, Hot Standby, Operating Power

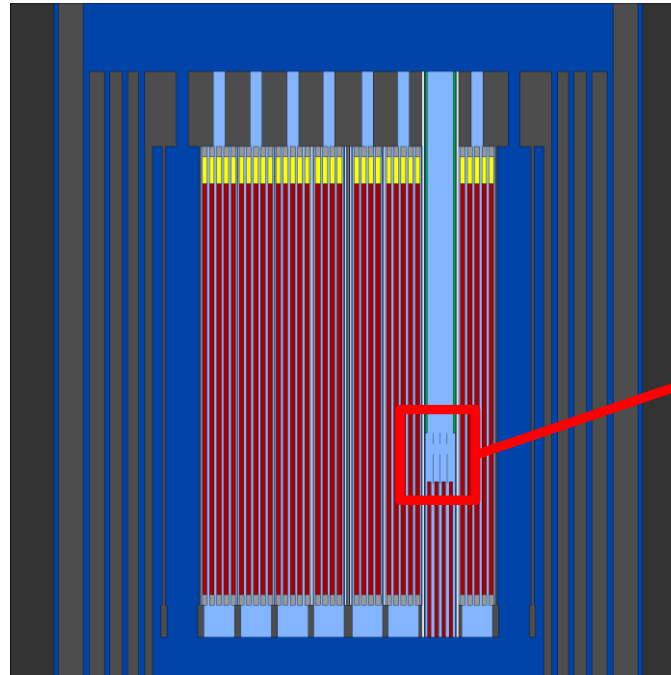


Models - Serpent and KMACS

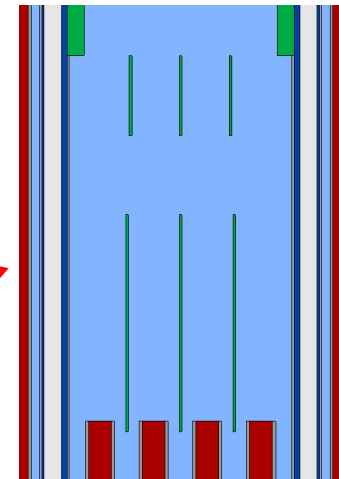
- Models were set up for the CZP state: 294 K, 0.99803 g/cm^3
 - Serpent Reference** model with detailed modelling of flux suppressors (cross-shaped absorber plates made from stainless steel + 1.35% B-10)
 - Serpent Simplified** model, flux suppressors replaced with absorber can → for better comparability with the KMACS model
 - KMACS** model with few group constants from infinite lattice models



Top view of reference model



Side view of reference model



Detail view of the flux suppressors

Results - Integral Quantities

- Multiplication factors – Fuel Followers and Transient Rod withdrawn:

	Serpent Reference	Serpent Simplified	KMACS
Multiplication factor	1.11724(6)	1.11804(6)	1.11184

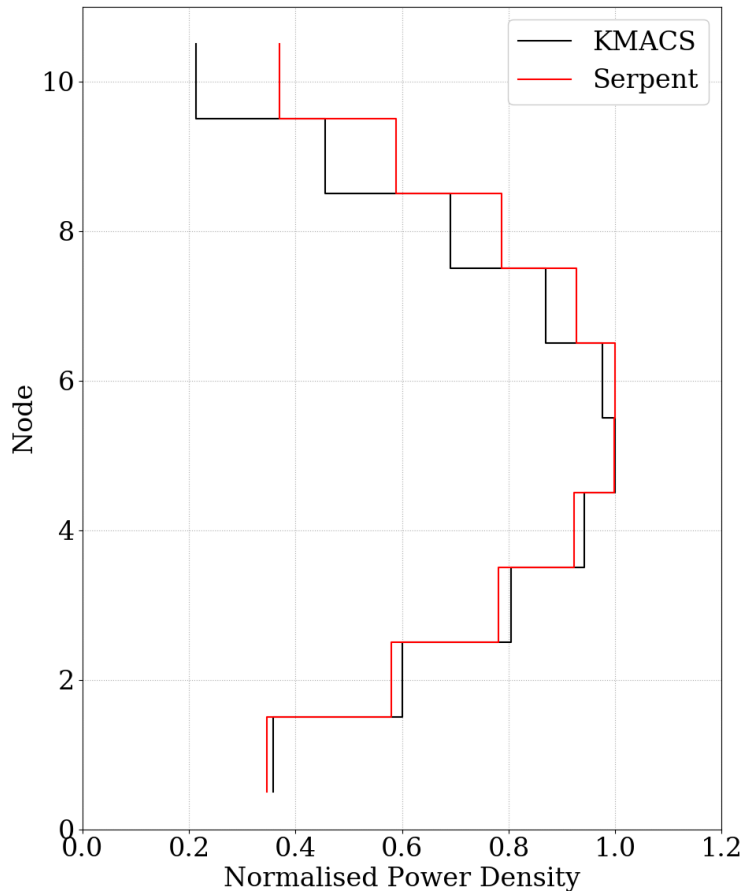
- Critical Position of the Fuel Followers (from bottom of active core):

	Serpent Reference	Experiment	Serpent Simplified	KMACS
FF Crit. Position [cm]	38.248	37.084	29.406	29.136

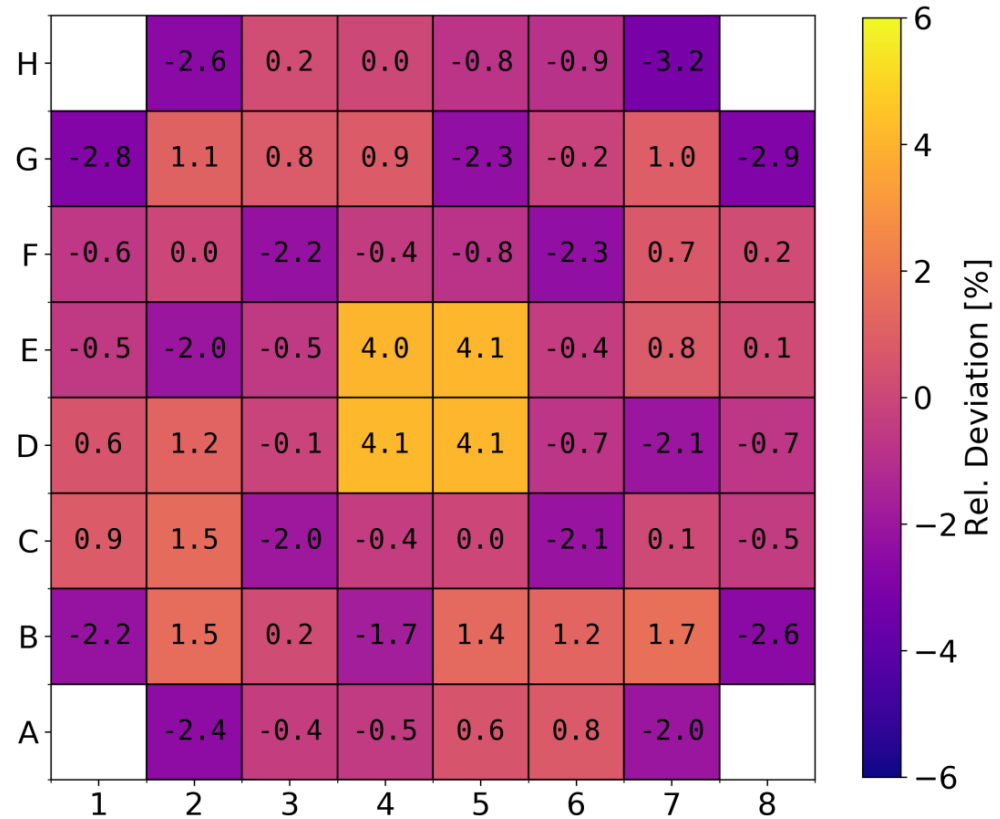
- Kinetic data from the reference model – FF and TR withdrawn:

Beta	2.355E-04	1.254E-03	1.226E-03	2.804E-03	1.239E-03	5.168E-04	Total: 0.00727574
Lambda	1.335E-02	3.261E-02	1.211E-01	3.056E-01	8.607E-01	2.892E+00	

Radial Power Distribution at All Rods Out State

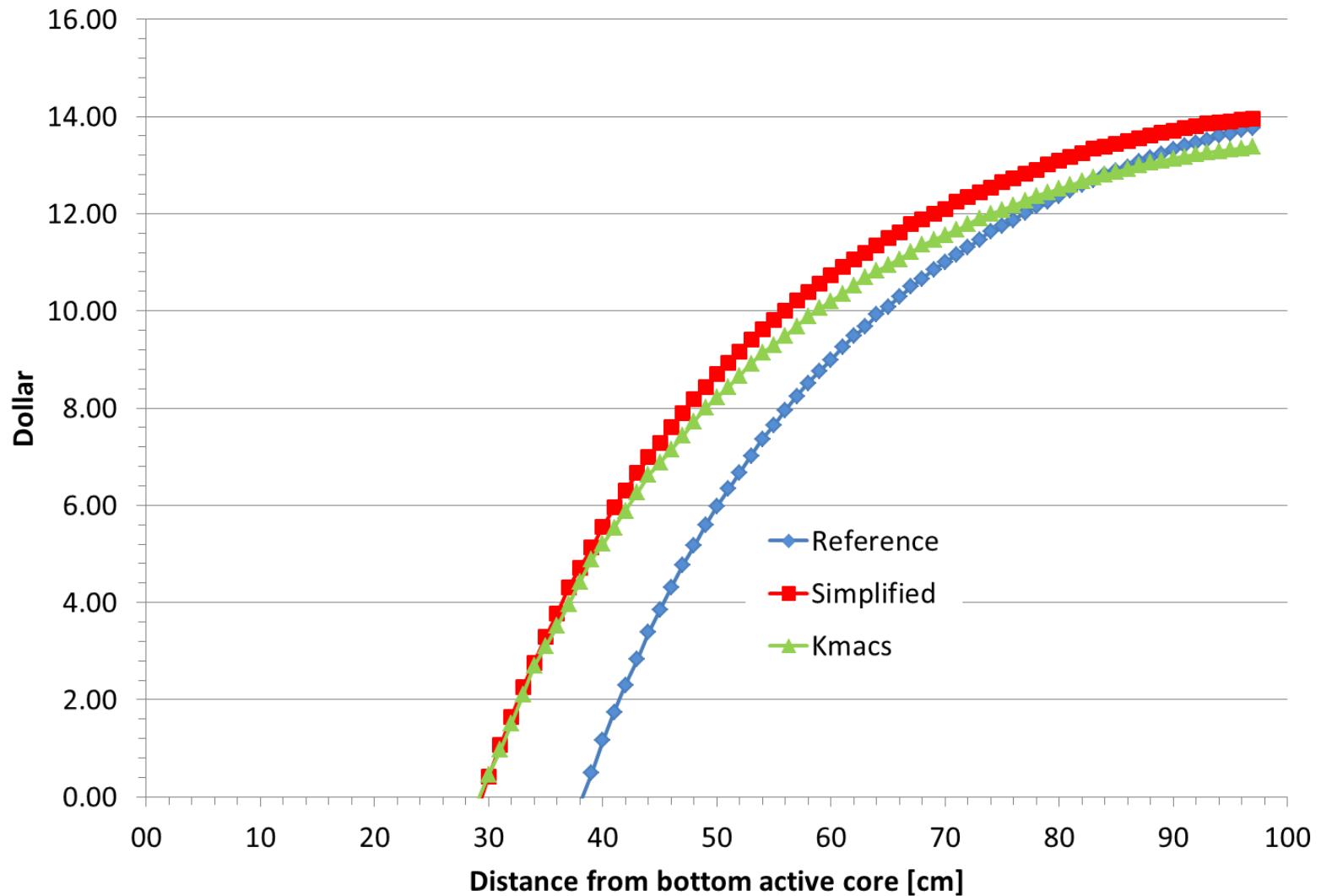


Axial distribution of normalised power density

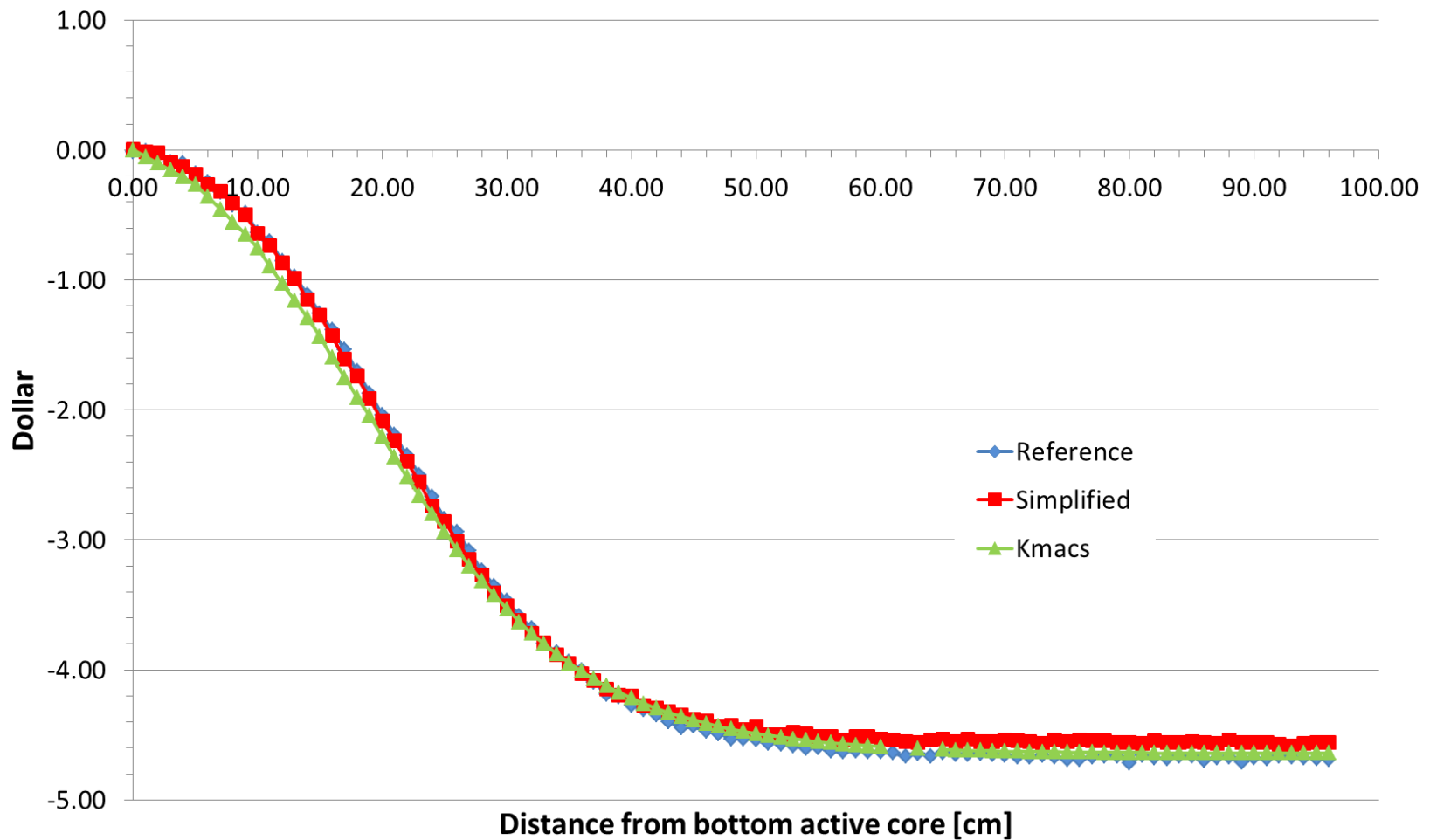


Rel. deviation between KMACS and Serpent

CR Worth – Fuel Followers



CR Worth – Transient Rod



Conclusions and Outlook

- Reference Serpent model and simplified Serpent model were built for CZP state
- Model built for the GRS core simulator KMACS with few-group constants from infinite-lattice calculations
- Preliminary results obtained:
 - Multiplication factors of the Serpent models and of the KMACS model at All Rods Out state → reasonable agreement
 - Critical position of the fuel followers:
 - About 1 cm deviation between the reference Serpent model and the experimental value
 - Good agreement between the simplified Serpent model and the KMACS model
 - Fuel followers worth and transient rod worth with the various models

Next steps:

- In-depth analyses of the static models for different reactor conditions
- Transient calculations